# A Novel Scheme for Support Identification and Iterative Sampling of Bandlimited Graph Signals



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### BACKGROUND

- Graph Signal Processing
  - Modeling network processes by exploiting the underlying graph structur
  - > Applications: sensor and social networks, transportation systems, gene regulatory networks
- Sampling and Reconstruction
  - > Selecting a *small representative* subset of graph nodes
  - > Applications: constrained sensing in sensor networks, data summarizatio

#### Notation and model

 $\mathbf{x} \in \mathbb{R}^N$  : signal on graph  $\mathcal{G}$  with N nodes,  $\mathbf{C} \in \{0,1\}^{k imes N}$  Sampling matrix A: adjacency matrix of  $\mathcal{G}$ 

- V: basis of the graph signal (here, eigenvectors of the Laplacian matrix **L**)  $\bar{\mathbf{x}} = \mathbf{V}^{\top}\mathbf{x}$  : graph Fourier transform, k-sparse (bandlimited), support  $\mathcal{K}$  $\mathbf{U} \in \mathbb{R}^{N \times k}$  : submatrix of  $\mathbf{V}$  containing columns indexed by  $\mathcal{K}$
- $\mathbf{y} = \mathbf{x} + \mathbf{n}$  : measurement model, **n** bounded noise with  $\mathbb{E}[\mathbf{nn}^{\top}] = \mathbf{Q}$
- Goal: finding a *good* sampled signal  $\tilde{\mathbf{x}} = \mathbf{C}\mathbf{x}$  for perfect reconstruction:

$$\hat{\mathbf{x}} = \mathbf{U}\bar{\mathbf{x}}_{\mathcal{K}} = \mathbf{U}(\mathbf{C}\mathbf{U})^{-1}\tilde{\mathbf{x}}$$

- Prior work [1] and [2] based on using uniform and leverage score random sampling : nonzero probability of failure, require more than k samples
- Our approach: Iterative scheme based on orthogonal matching pursuit (OMF)
- Support identification from *historical observations* of the graph signal

### ITERATIVE SELECTION SAMPLING

- Necessary and sufficient condition for perfect recovery: *invertibility* of  $\mathbf{CU}$
- Make it invertible by construction:
  - > select a *residual node*  $\ell \in [N]$  (to be excluded from the sampling set)
  - > suggestion for residual:  $\ell = \operatorname{argmin}_{j \in [N]} \|\mathbf{u}_j\|_2$
  - $\succ$  iteratively identify a sampling node and construct sampling set S

$$j_s = \arg\max_{j \in \mathcal{N} \setminus \mathcal{S}} \frac{|\mathbf{r}_{i-1}^{\top} \mathbf{u}_j|^2}{\|\mathbf{u}_j\|_2^2}$$

- $\succ \mathbf{r}_i = \mathbf{P}_{\mathcal{S}}^{\perp} \mathbf{u}_{\ell}$ : the residual vector initialized at  $\mathbf{r}_0 = \mathbf{u}_{\ell}$
- $\succ \mathbf{P}_{\mathcal{S}}^{\perp} = \mathbf{I}_N \mathbf{U}_{\mathcal{S},r}^{\top} (\mathbf{U}_{\mathcal{S},r}^{\top})^{\dagger}$ : the projection operator to complement of the subspace spanned by  $\mathbf{U}_{\mathcal{S},r}$  (rows of U indexed by  $\mathcal{S}$ )

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	PERFORMANCE ANALYSIS
res	<ul> <li>Proposed scheme guarantees perfect recovery in noiseless case for all connected graphs with general structures and with normal adjacency.</li> </ul>
	Theorem 1:
	Let $S$ be the sampling set constructed by Algorithm 1 and let be C the corresponding sampling matrix such that $ S  = k$ . Then, the matrix CU invertible.
on	Proof's remarks:
	$\succ$ An inductive argument
	> Iterative selection of linearly independent $\mathbf{u}_i$ 's
	Zero residual norm only after the last iteration
	Sampling under bounded noise
	• Assumption: $\ \mathbf{n}\ _2 \leq \epsilon_n$
	<ul> <li>Explicit bound on reconstruction error</li> </ul>
	$\ \hat{\mathbf{x}} - \mathbf{x}\ _2 \leq \sigma_{\max}((\mathbf{U}_{\mathcal{S},r}^{\top}\mathbf{Q}_{\mathcal{S}}^{-1}\mathbf{U}_{\mathcal{S},r})^{-1}\mathbf{U}_{\mathcal{S},r}^{\top}\mathbf{Q}_{\mathcal{S}}^{-1})\epsilon_{\mathbf{n}}$
	<ul> <li>Guaranteed existence of inverse matrices under Algorithm 1</li> </ul>
	<ul> <li>Preserving statistical characteristics (e.g. whiteness) of effective noise</li> </ul>
	SUPPORT IDENTIFICATION
P)	Support recovery given D bistorical templates $\mathbf{V}$ [1] $= -P_1 \in \mathbb{D}^N$
	shared support from noisy observations $\mathbf{Y} = \mathbf{X} + \mathbf{N}$
	• Equivalent task: estimating sparse GFTs $\bar{\mathbf{X}} = [\bar{\mathbf{x}}^1, \cdots, \bar{\mathbf{x}}^P] = \mathbf{V}^T \mathbf{X}$
	<ul> <li>Proposed optimization based on <i>block sparsity</i> of <math>\bar{\mathbf{X}}</math>:</li> </ul>
	$\min_{\bar{\mathbf{X}}} \ \bar{\mathbf{X}} - \mathbf{V}^T \mathbf{Y}\ _F^2  \text{s.t.}  \ \bar{\mathbf{X}}\ _{2,0} \le k,$
	• Closed-form solution via row-wise $l_2$ norm thresholding on

 $\bar{\mathbf{Y}} = \mathbf{V}^T \mathbf{Y}$ 

$$\bar{\mathbf{X}}(i,:)^{\star} = \begin{cases} \bar{\mathbf{Y}}(i,:) & \|\bar{\mathbf{Y}}(i,:)\|_2 \ge k^{\text{th}} \text{ largest } \ell_2 \text{ norm} \\ \mathbf{0} & \text{o.w.} \end{cases}$$

#### **Theorem 2**

Assume — is orthogonal. Under bounded noise assumption, the GFTs  $\overline{\mathbf{X}}$  and support  $\mathcal{K}$  are identifiable if

$$\min_{i \in \mathcal{K}} \quad \|\bar{\mathbf{X}}(i,:)\|_2 > 2\epsilon_{\mathbf{n}} \sqrt{P}.$$

- Perfect support identification *in the absence of noise* with P = 1
- Easier satisfiability of the established sufficient condition for larger P





