

Sampling and Reconstruction of Graph Signals via Weak Submodularity and Semidefinite Relaxation

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BACKGROUND

- Graph Signal Processing
 - Modeling network processes by exploiting the underlying graph structures
 - Applications: sensor and social networks, transportation systems, gene regulatory networks

Sampling and Reconstruction

- Selecting a *small representative* subset of graph nodes
- Applications: resource-constrained sensing in sensor networks, data summarization

Notation and model

$\mathbf{x} \in \mathbb{R}^N$: a graph signal with N nodes, *non-stationary*

\mathbf{A} : an adjacency matrix of the graph

\mathbf{V} : a basis of the graph signal (here, eigenvectors of the Laplacian matrix \mathbf{L})

$\bar{\mathbf{x}} = \mathbf{V}^\top \mathbf{x}$: graph Fourier transform, k -sparse (*bandlimited*), support K , $\mathbb{E}[\bar{\mathbf{x}}\bar{\mathbf{x}}^\top] = \mathbf{P}$

$\mathbf{U} \in \mathbb{R}^{N \times k}$: a submatrix of \mathbf{V} containing columns indexed by K

$\mathbf{y} = \mathbf{x} + \mathbf{n}$: measurement model, \mathbf{n} Gaussian noise with $\mathbb{E}[\mathbf{n}\mathbf{n}^\top] = \sigma^2 \mathbf{I}_N$

MSE Formulation of the graph sampling problem

$$\min_S \text{Tr}(\bar{\Sigma}_S) \quad \text{s.t.} \quad S \subseteq \mathcal{N}, |S| \leq k \quad \bar{\Sigma}_S = (\mathbf{P}^{-1} + \sigma^{-2} \mathbf{A}_{S,r}^\top \mathbf{A}_{S,r})^{-1}$$

➤ *NP-hard problem!*

- Prior work [1] based on *greedy* heuristics: guarantees *only* in stationary case
- Our approaches: SDP relaxation and randomized greedy

A SDP RELAXATION FORMULATION

Solve

$$\min_{\mathbf{z}, \mathbf{B}} \text{Tr}(\mathbf{B}) \quad \text{s.t.} \quad 0 \leq z_i \leq 1, \sum_{i=1}^n z_i \leq k, \mathbf{B} \succeq \mathbf{0}.$$

$$\bar{\Sigma}_z = \left(\mathbf{P}^{-1} + \sigma^{-2} \sum_{i=1}^n z_i \mathbf{u}_i \mathbf{u}_i^\top \right)^{-1} \quad \mathbf{B} = \begin{bmatrix} \mathbf{C} & \mathbf{I} \\ \mathbf{I} & \bar{\Sigma}_z^{-1} \end{bmatrix}.$$

Round \mathbf{z} to find the selected subset

WEAK SUBMODULARITY OF THE MSE

- [*Submodularity*] Function $f: 2^X \rightarrow \mathbb{R}$ is submodular if for $S \subseteq T \subset X, j \in X \setminus T$

$$f_j(S) = f(S \cup \{j\}) - f(S) \geq f(T \cup \{j\}) - f(T) = f_j(T)$$

- [*Monotonicity*] Function $f: 2^X \rightarrow \mathbb{R}$ is monotone if $f(S) \leq f(T)$ for $S \subseteq T \subset X$

- [*Curvature*] Let $\mathcal{X}_l = \{(S, T, i) | S \subset T \subset X, i \in X \setminus T, |T \setminus S| = l, |X| = n\}$.

Then, the maximum element-wise curvature is defined as

$$C_{\max} = \max_{l \in [n-1]} \max_{(S, T, i) \in \mathcal{X}_l} f_i(T) / f_i(S)$$

- An equivalent formulation of graph sampling:

$$\max_S f(S) = \text{Tr}(\mathbf{P} - \bar{\Sigma}_S) \quad \text{s.t.} \quad S \subseteq \mathcal{N}, |S| \leq k. \quad (1)$$

WEAK SUBMODULARITY OF THE MSE

Theorem 1:

The objective function $f(S)$ is a monotonically increasing set function, $f(\emptyset) = 0$ and

$$f_j(S) = \frac{\mathbf{u}_j^\top \bar{\Sigma}_S^2 \mathbf{u}_j}{\sigma^2 + \mathbf{u}_j^\top \bar{\Sigma}_S \mathbf{u}_j} \quad \bar{\Sigma}_{S \cup \{j\}} = \bar{\Sigma}_S - \frac{\bar{\Sigma}_S \mathbf{u}_j \mathbf{u}_j^\top \bar{\Sigma}_S}{\sigma^2 + \mathbf{u}_j^\top \bar{\Sigma}_S \mathbf{u}_j}.$$

Further,

$$C_{\max} \leq \frac{\lambda_{\max}^2(\mathbf{P})}{\lambda_{\min}^2(\mathbf{P})} \left(1 + \frac{\lambda_{\max}(\mathbf{P})}{\sigma^2} \right)^3$$

- Intuition: A *well-conditioned* \mathbf{P} ensures *weak submodularity*

A RANDOMIZED GREEDY ALGORITHM

- An accelerated graph sampling scheme, inspired by the algorithm in [2] (only for submodular objectives and hence not MSE)
- Randomized step:
 - select a *random subset* R in each iteration with $|R| = \frac{N}{k} \log(1/\epsilon)$
 - essentially reducing the number of oracle calls
 - for $\epsilon = e^{-k}$ we obtain the greedy algorithm in [1]
 - speed gain of $k/\log(1/\epsilon)$ compared to the state-of-the-art scheme in [1]

Algorithm 1 Randomized Greedy Algorithm for Graph Sampling

- Initialize $S = \emptyset, \bar{\Sigma}_S = \mathbf{P}$.
- while** $|S| < k$
- Choose R by sampling $s = \frac{N}{k} \log(1/\epsilon)$ indices uniformly from $\mathcal{N} \setminus S$
- $j_s = \arg\max_{j \in R} \frac{\mathbf{u}_j^\top \bar{\Sigma}_S^2 \mathbf{u}_j}{\sigma^2 + \mathbf{u}_j^\top \bar{\Sigma}_S \mathbf{u}_j}$
- $\bar{\Sigma}_{S \cup \{j_s\}} = \bar{\Sigma}_S - \frac{\bar{\Sigma}_S \mathbf{u}_{j_s} \mathbf{u}_{j_s}^\top \bar{\Sigma}_S}{\sigma^2 + \mathbf{u}_{j_s}^\top \bar{\Sigma}_S \mathbf{u}_{j_s}}$
- Set $S \leftarrow S \cup \{j_s\}$
- end while**

PERFORMANCE GUARANTEES

- Guarantee on expected MSE of selected nodes:

Theorem 2:

Let $\alpha = (1 - e^{-\frac{1}{c}} - \frac{\epsilon^\beta}{c})$ where $e^{-k} \leq \epsilon < 1, c = \max\{1, C\}$, and

$\beta = 1 + \max\{0, \frac{s}{2n} - \frac{1}{2(n-s)}\}$. Let S be the set returned by the randomized greedy algorithm and let O denote the optimal set of nodes. Then,

$$\mathbb{E}[\text{Tr}(\bar{\Sigma}_S)] \leq \alpha \text{Tr}(\bar{\Sigma}_O) + (1 - \alpha) \text{Tr}(\mathbf{P}_x).$$

- Intuition: average MSE over ensemble of sampling problem is near optimal
- Proof idea: in each iteration, R with *high probability* contains a node indexed by O if $|R| = \frac{N}{k} \log(1/\epsilon)$.
- Next, a *probably approximately correct (PAC)* view:
 - Effect of randomization: in l^{th} iteration $f_{j_{rg}}(S_{rg}) = \eta_l f_{j_g}(S_g)$ where $0 < \eta_l \leq 1$ are random variables.

PERFORMANCE GUARANTEES

Theorem 3:

Instate the notation and hypotheses of Theorem 2. Assume $\{\eta_i\}_{i=1}^k$ are independent such that $\mathbb{E}[\eta_i] \geq \mu$. Then, for all $0 < q < 1$ and for some $C > 0$ with probability at least $1 - e^{-C^k}$ it holds that

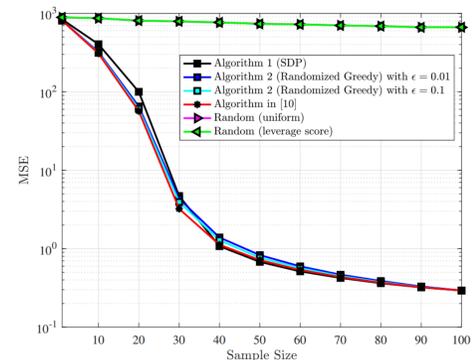
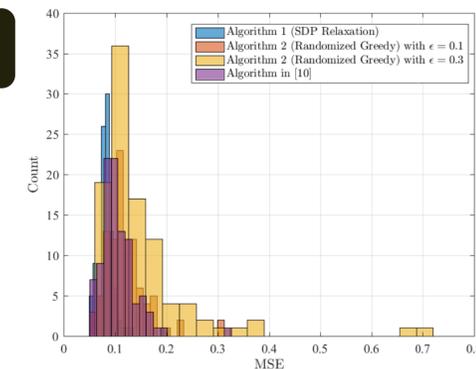
$$\text{Tr}(\bar{\Sigma}_{S_{rg}}) \leq (1 - e^{-\frac{(1-q)\mu}{c}}) \text{Tr}(\bar{\Sigma}_O) + e^{-\frac{(1-q)\mu}{c}} \text{Tr}(\mathbf{P}).$$

Intuition: MSE for a single sampling problem is also near optimal

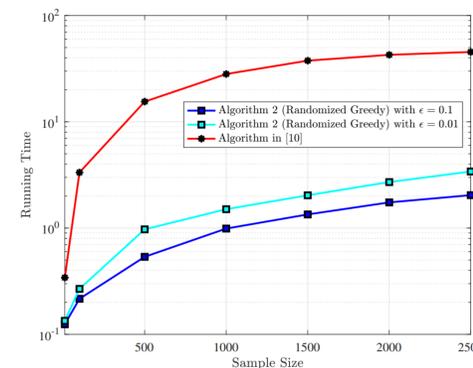
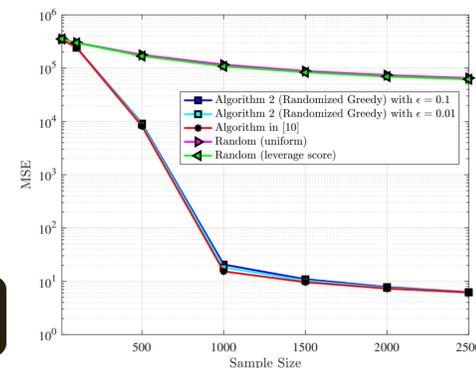
Proof idea: Applying *Bernstein inequality* on sum of marginal gains

RESULTS

Simulated Erdos-Renyi graph



Real-world graph: Minnesota road network



CONCLUSION

Our contributions:

- proved *weak submodularity* of (1) for non-stationary graph signals
- proposed an SDP relaxation framework for sampling and reconstruction
- proposed a *randomized greedy* algorithm with performance guarantees
- demonstrated superiority of the proposed methods using simulated and real-world graphs

Future work:

- Handling unknown support, extension to nonlinear models

[1] L. FO Chamon and A. Ribeiro, "Greedy sampling of graph signals," IEEE TSP, 2018.

[2] B. Mirzasoleiman, A. Badanidiyuru, A. Karbasi, J. Vondrak, and A. Krause, "Lazier than lazy greedy," in AAAI, 2015.