Physical-Layer Security via Distributed Beamforming in the Presence of Adversaries with Unknown Locations

How can a group of robots securely communicate with a client in the presence of multiple adversaries that eavesdrop on the transmission?



Adversary a_i at the unknown far-field direction Possible directions: $I_i \subseteq [-\pi, \pi)$

Key challenges:

- Unknown adversary locations
- Limited individual transmission power

Assumptions:

- Free space propagation
- L adversaries in the environment
- Communication to far-field region
- Possible adversary directions are expressed by direction intervals

Yagiz Savas, Abolfazl Hashemi, Abraham P. Vinod, Brian M. Sadler, Ufuk Topcu





JTONOMOUS SYSTEMS GROUP

